

Applications of SMT solvers

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- ◆ SMT solvers are finding their way in many different application domains
- ◆ Reasons for success?
 - allows to deal with richer representation
 - increase capacity by working above the boolean level
- ◆ Successful applications in various fields
 - verification of pipelined microprocessors
 - equivalence checking of Microcode
 - software verification
 - whitebox testing for security applications
 - design space exploration, configuration synthesis
 - discovery of combinatorial materials

Focus on three main areas

- ◆ SMT-based for verification of complex systems
 - See also tutorials at SAT/SMT'11, FMCAD'12, ICAPS'13
- ◆ SMT-based temporal planning
 - Scheduling with uncertainty
 - The role of quantification
- ◆ SMT-based reliability assessment
 - Analysis of redundancy architectures
 - The role of EUF and predicate abstraction

SMT-based verification of Hybrid Systems

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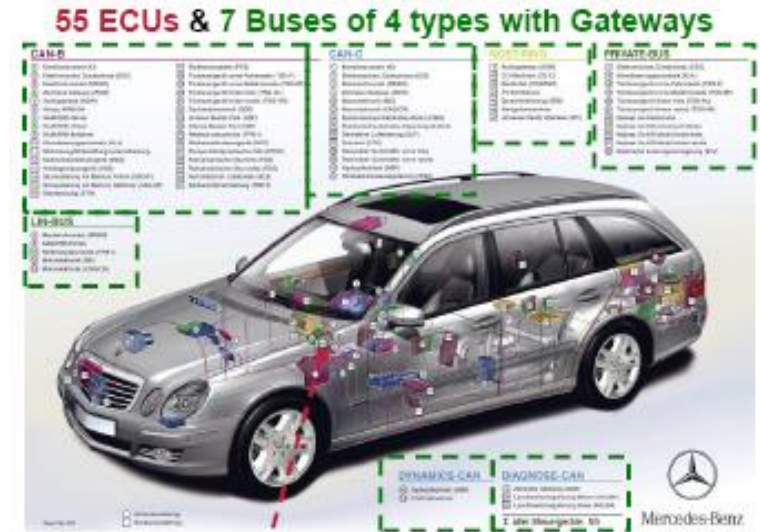
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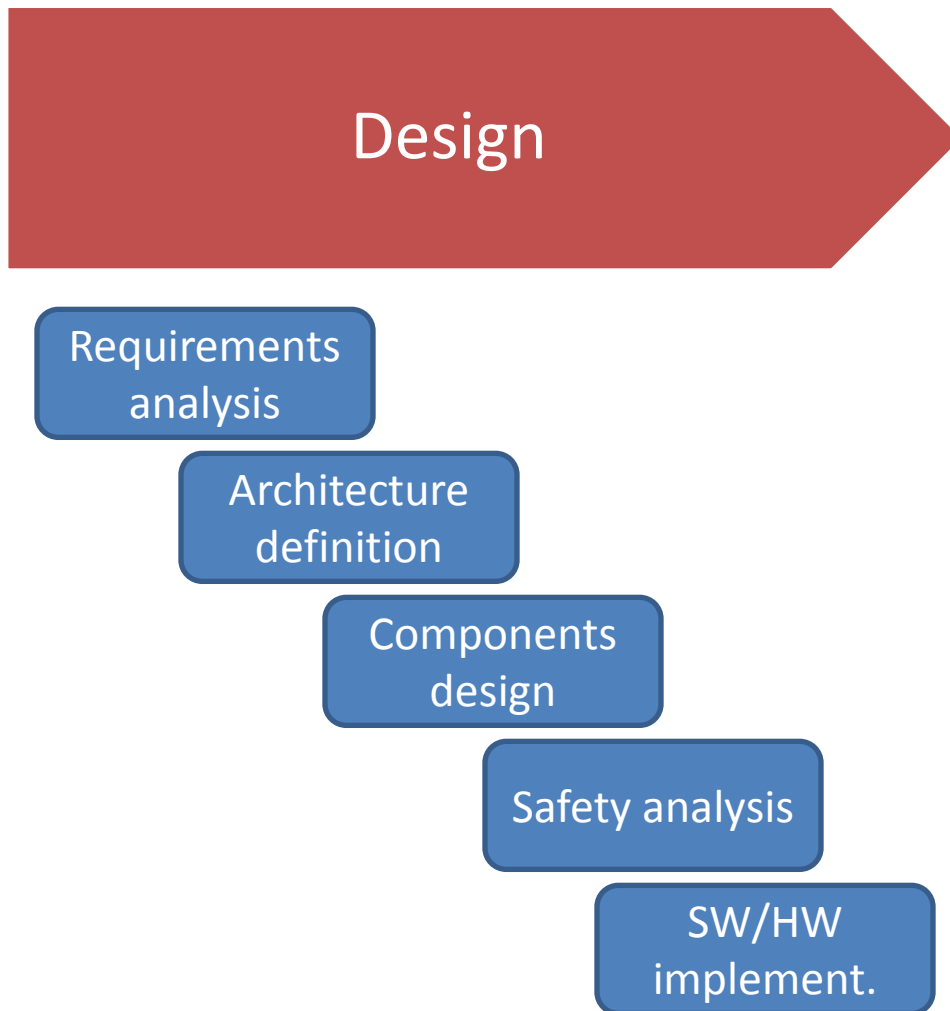
Joint work with Sergio Mover and Stefano Tonetta

- ◆ The need for verification
 - Very complex systems
- ◆ Verification in a broader sense
 - Rigorous analysis of the behaviour of dynamic systems
- ◆ Hybrid automata
 - A uniform and comprehensive formal model
- ◆ Satisfiability Modulo Theories
 - Higher level symbolic modeling
 - Efficient engines: SAT + constraint solving
- ◆ SMT-based Verification
 - Many effective complementary algorithms

The Design Challenge

- ◆ Designing complex systems
 - Automotive
 - Railways
 - Aerospace
 - Industrial production
- ◆ Sources of complexity:
 - Hundreds of functions
 - Networked control
 - Real-time constraints
 - Complex execution model with mixture of real-time and event-based triggers
 - System composed of multiple heterogeneous subsystems
 - Critical Functions:
 - » ABS, drive-by-wire
 - » Operate switches, level crossings, lights
 - » Manage on-board power production
 - Conflicting objectives:
 - » Avoid crashes vs move trains





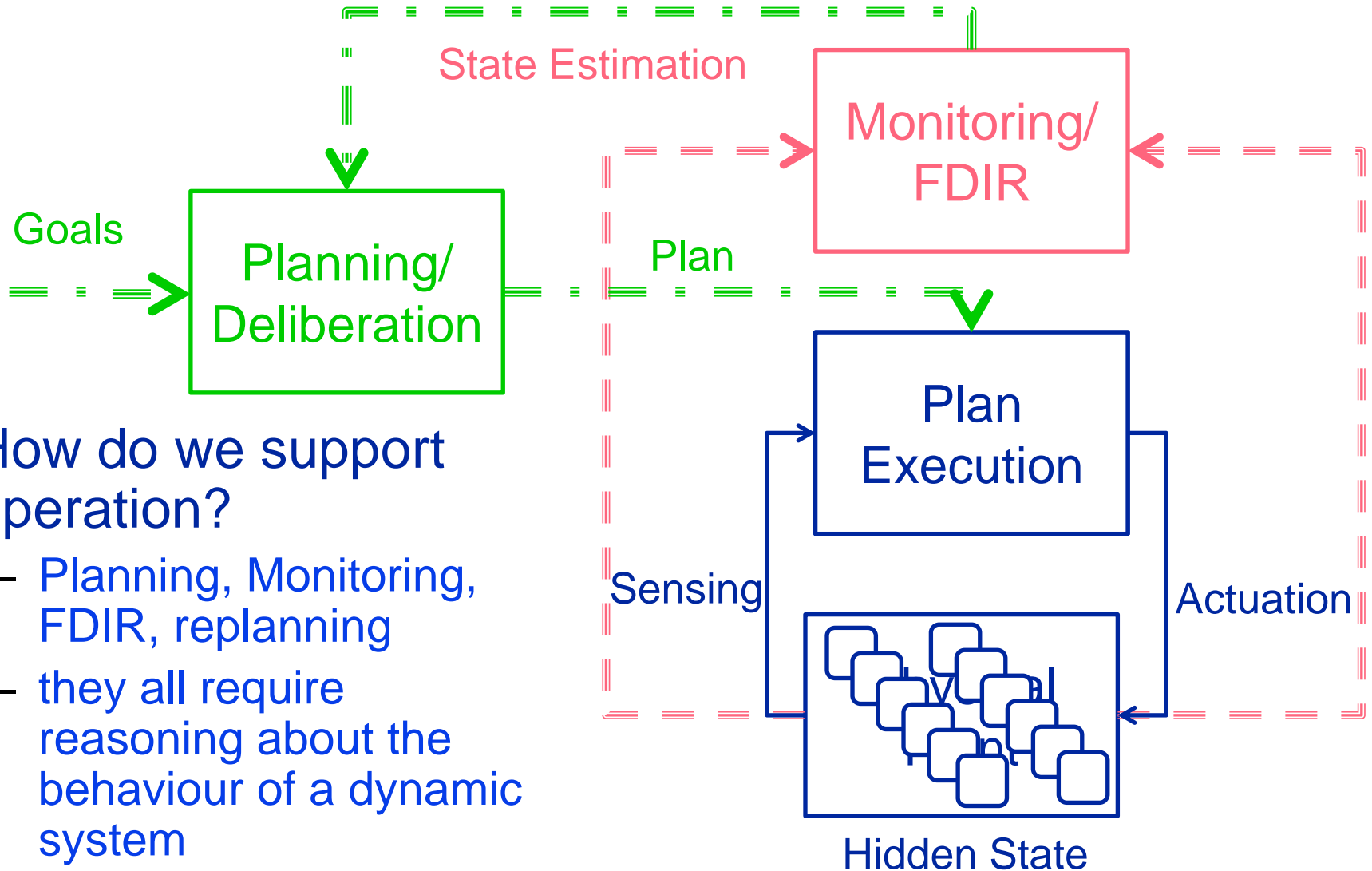
- ◆ How do we support the design?
- ◆ Requirements validation:
 - Are the requirements flawed?
- ◆ Functional correctness
 - Does the system satisfy the requirements?
- ◆ Safety assessment
 - Is the system able to deal with faults?

From design to operation...

- ◆ **Planning**
 - plan how to achieve desired “firing” sequence
 - retrieve pipes from holds, pre-weld, send to firing line, final weld
- ◆ **Execution Monitoring**
 - welding may fail, activities can take more time than expected
 - plant may fail
- ◆ **Fault Detection, Fault Identification/Isolation**
 - is there a problem? where is it?
- ◆ **Fault Recovery**
 - put off-line problematic equipment
- ◆ **Replanning**
 - identify alternative course of actions, e.g. reroute pipes

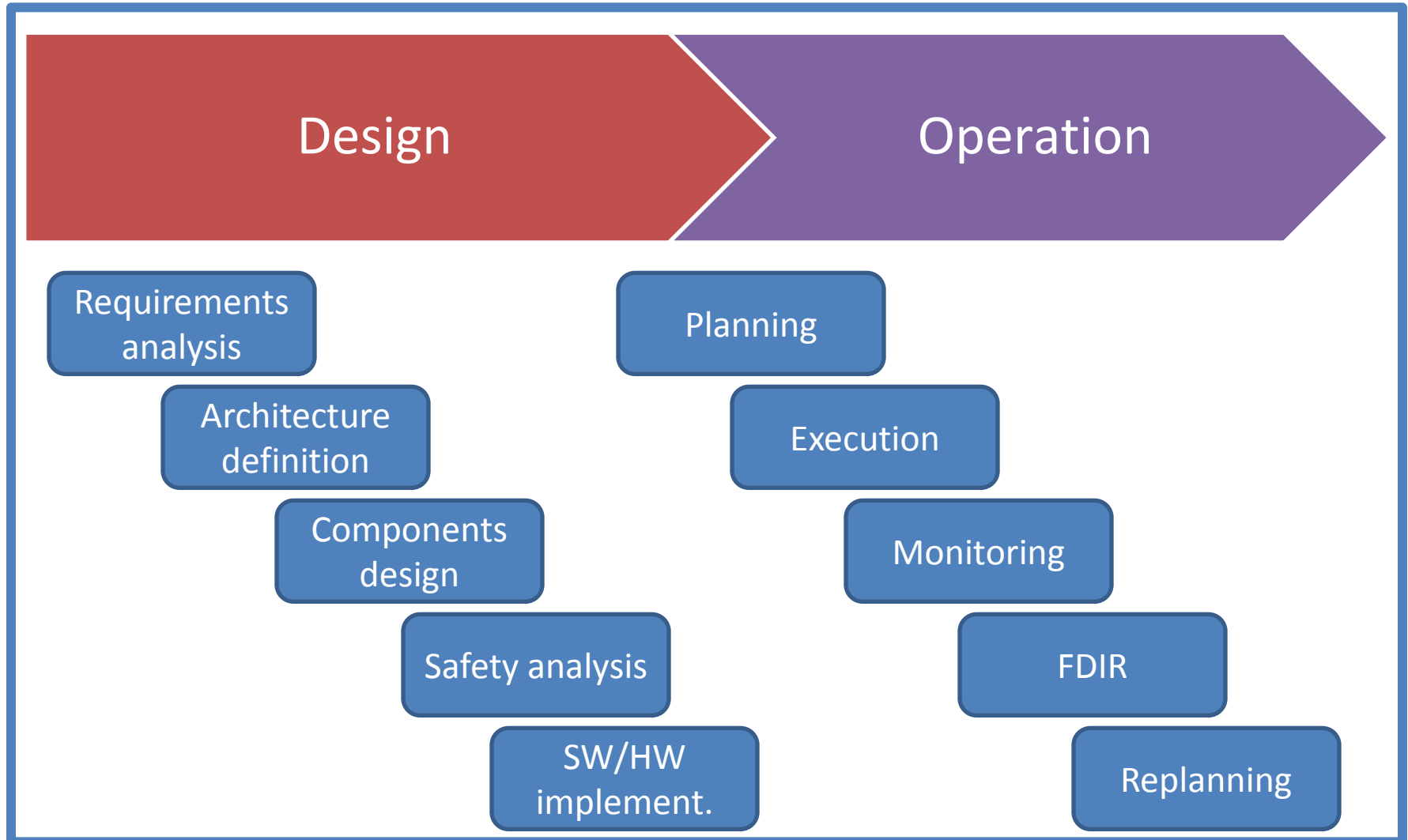


Complex systems operation



- ◆ How do we support operation?
 - Planning, Monitoring, FDIR, replanning
 - they all require reasoning about the behaviour of a dynamic system

Life Cycle of Complex Systems



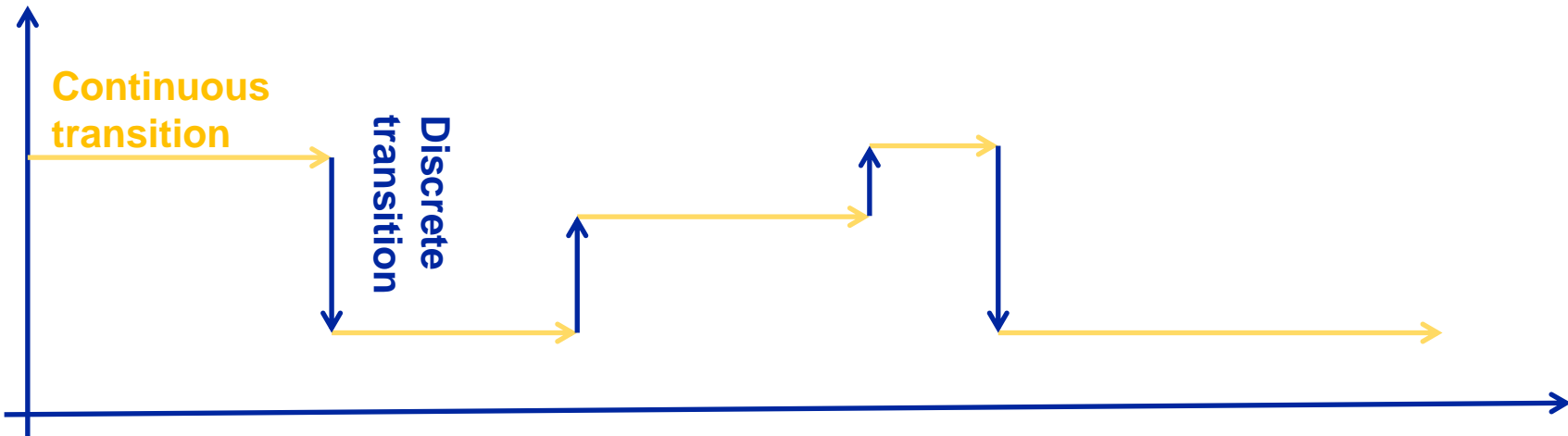
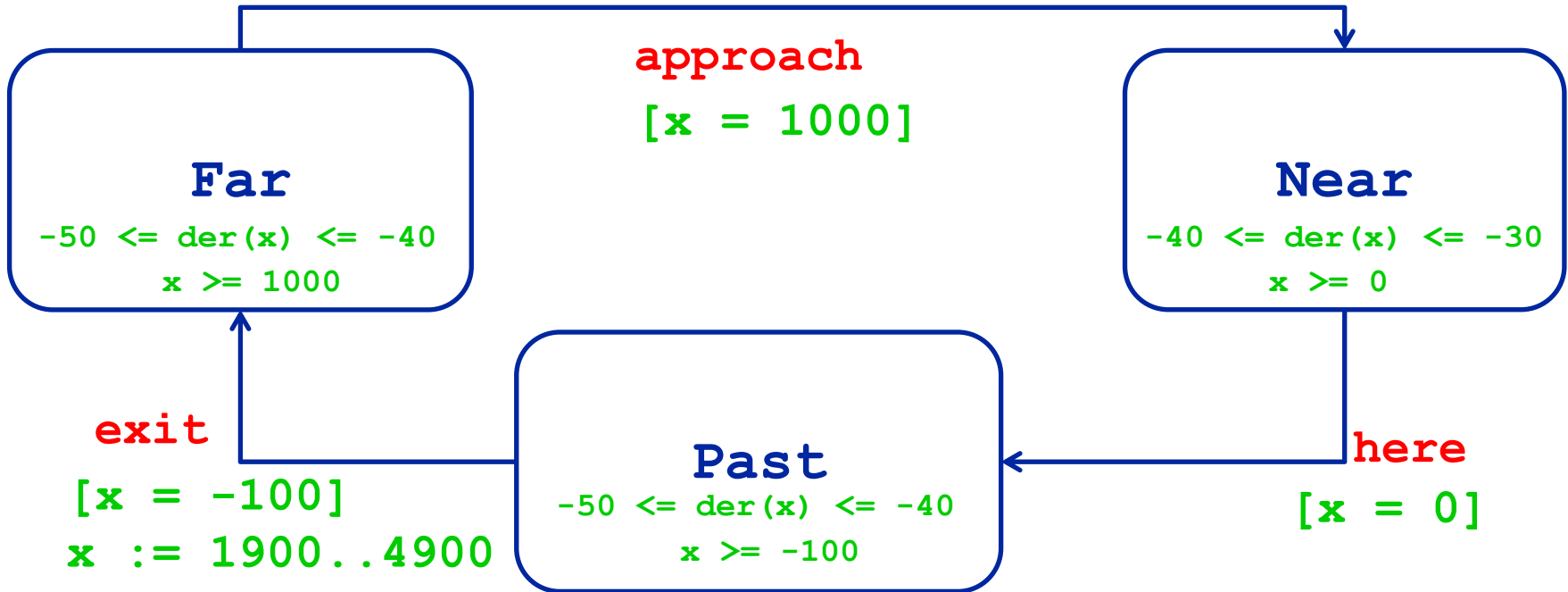
The “formal” way

- ◆ The design-operation continuum
 - Both design and operation tasks require the analysis of the behaviour of dynamic systems over time
 - In fact, they often require the analysis of the *same* dynamic systems
 - the analysis must be “rigorous” (predictability, certification)

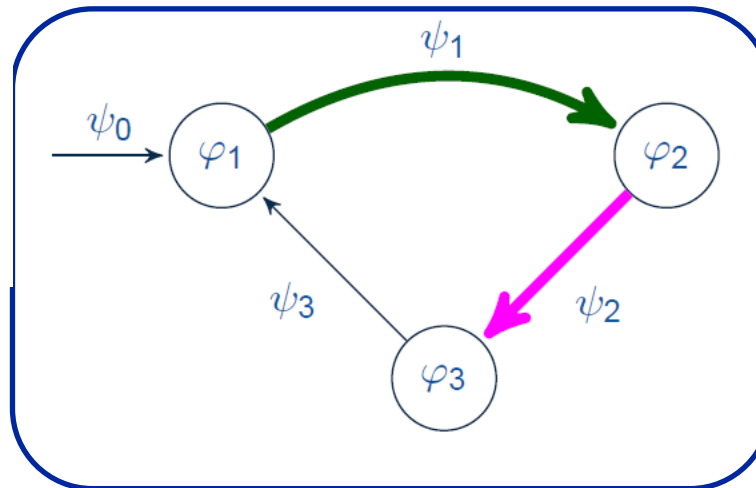
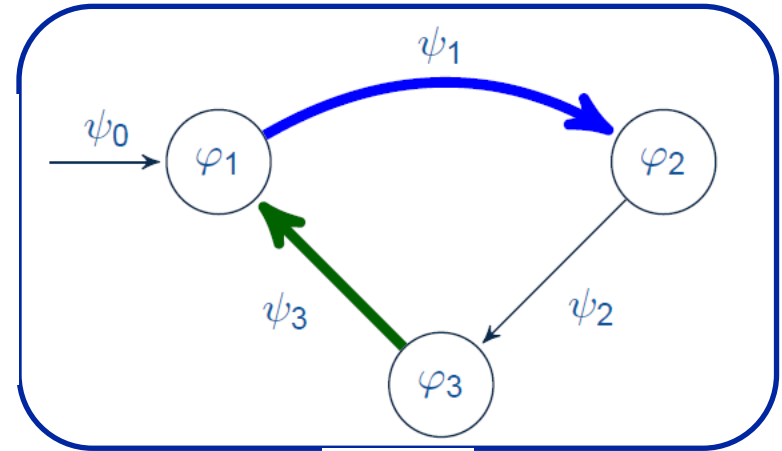
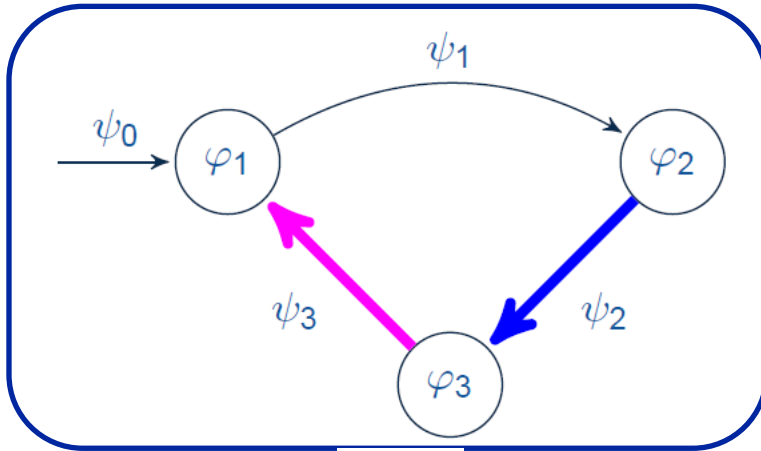
- ◆ We need a rich formalism
 - to represent the behaviour of complex systems
 - to provide the reasoning tasks required for design and for operation

- ◆ Representation challenges
 - Nondeterministic behaviours
 - Possible Faults
 - Operation in degraded modes
 - Limited Observability
 - Parallel actions/tasks
 - » Start actuations in different subsystems
 - Time
 - » Time taken by procedures
 - » e.g. moving, welding, checking, ...
 - Resources
 - » Power consumption, space, bandwidth, memory, ...

Hybrid automata



Networks of hybrid automata



Properties of hybrid automata

- ◆ Well founded, comprehensive and well studied
 - Clear definition of behaviors of model
 - Which states are reachable
- ◆ Temporal properties to express scenarios and requirements
 - *never two processes in critical region*
 - *always if req then within 5 sec response*
- ◆ Model checking
 - » Does the system satisfy the requirements?
- ◆ Temporal reasoning
 - » Strong/weak/dynamical controllability?
- ◆ Planning
 - » Find the inputs that will bring the system to required state
- ◆ The workhorse: satisfiability modulo theories

Satisfiability modulo theories

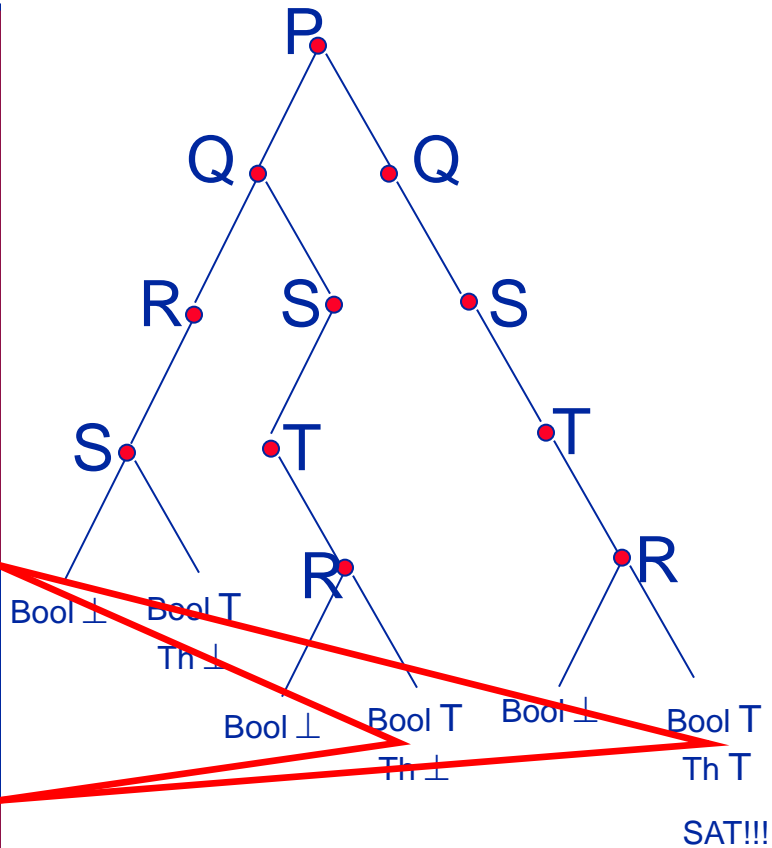
- ◆ Satisfiability of a first order formula ...
 - where the atoms are interpreted modulo a background theory
- ◆ Theories of practical interest
 - Equality Uninterpreted Functions (EUF)
 - » $x = f(y)$, $h(x) = g(y)$
 - Difference constraints (DL)
 - » $x - y \leq 3$
 - Linear Arithmetic
 - » $3x - 5y + 7z \leq 1$
 - » reals (LRA), integers (LIA)
 - Arrays (Ar)
 - » $\text{read}(\text{write}(A, i, v), j)$
 - Bit Vectors (BV)
 - Their combination

- ◆ An extension of boolean SAT
- ◆ Some atoms have non-boolean (theory) content
 - » $A1 : x - y \leq 3$
 - » $A2 : y - z = 10$
 - » $A3 : x - z \geq 15$
- ◆ Theory interpretation for individual variables, constants, functions and predicates
 - » if $x = 0, y = 20, z = 10$
 - » then $A1 = T, A2 = T, A3 = F$
- ◆ Interpretations of atoms are constrained
 - » $A1, A2$ and $A3$ can not be all true at the same time

- ◆ Boolean reasoning + constraint solving
 - SAT solver for boolean reasoning
 - theory solvers to interpret numerical constraints

SMT search space

P	T	$x - y \leq 3$
<hr/>		
P ₁	F	
P ₂	T	$y - z = 10$
Q	F	
R	T	$x - z \geq 15$
<hr/>		
R ₁	F	
S	F	$z - 2*w = 1$
<hr/>		
S ₁	T	



- ◆ In practice, the integration is very tight
 - SAT solver working as an enumerator
 - Theory solver follows the stack-based search
 - » Inconsistent partial assignments are pruned on the fly
 - » conflicts clauses learnt from theory reasoning
 - » used to drive search at the boolean level

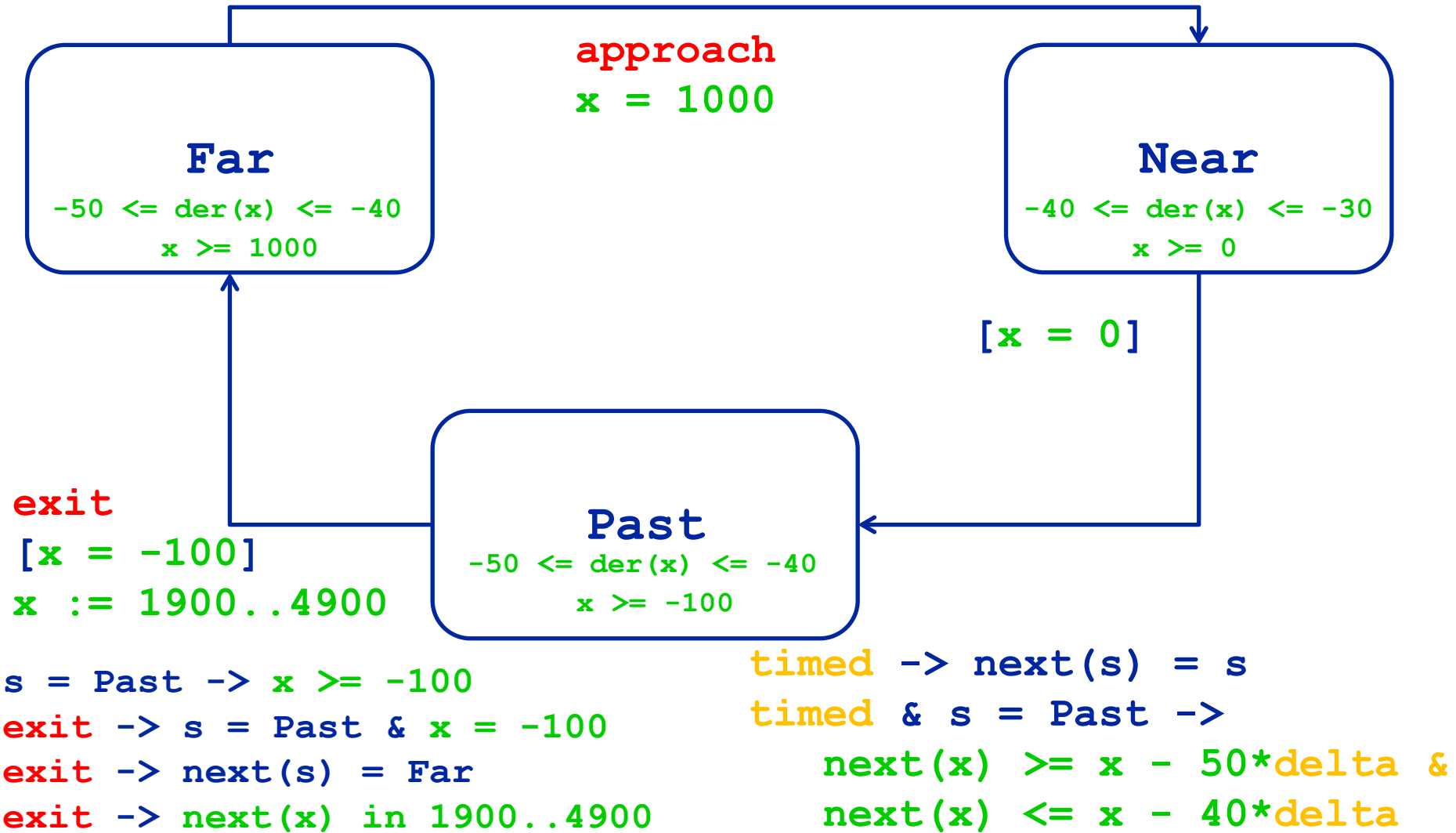
- ◆ Additional features
 - Model construction
 - Incremental interface
 - Unsatisfiable core
 - Proof production
 - Interpolation

- ◆ Satisfiability Modulo Theories: a sweet spot?
 - increase expressiveness
 - retain efficiency of boolean reasoning

- ◆ Trade off between expressiveness and reasoning
 - SAT solvers: boolean case, automated and very efficient
 - theorem provers: general FOL, limited automation

- ◆ Standard language and benchmarks
 - <http://www.smt-lib.org>
- ◆ Yearly competition
 - <http://www.smt-comp.org>
- ◆ Solvers
 - YICES, OpenSMT, MathSAT, Z3, CVC, ...

From HA to SMT formulae



The SMT representation

```

VAR s : { Past, Near, Far }
VAR x : real;
...
INIT x <= 5000
INIT s = Past
...
TRANS
s = Past -> x >= -100
exit -> s = Past
exit -> next(s) = Far
exit -> next(x) >= 1900
exit -> next(x) <= 4900
...
timed -> next(s) = s
timed -> next(x) >= x - 50*delta
timed -> next(x) <= x - 40*delta

```

Hybrid automata symbolically
represented by SMT formulae!

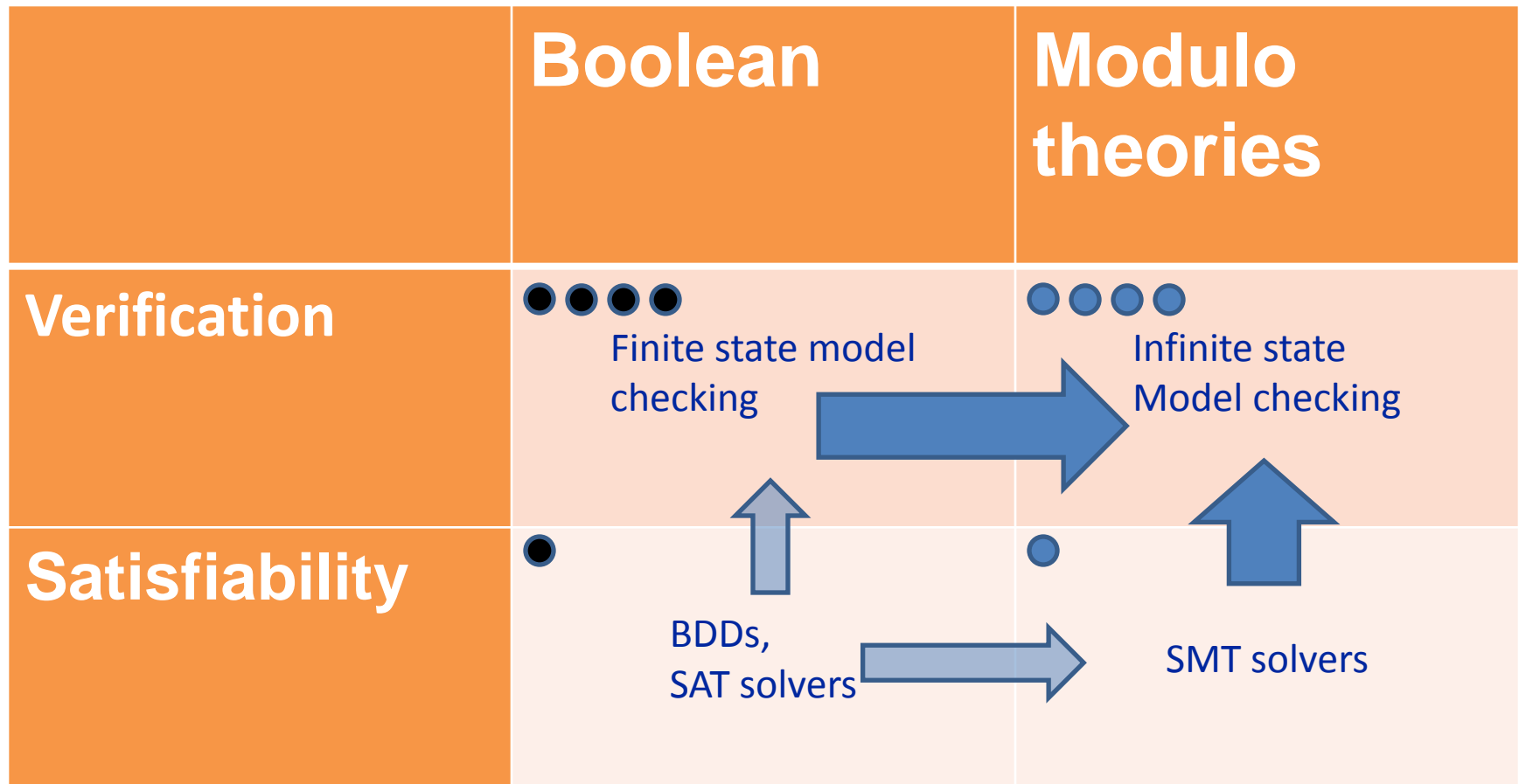
$I(X)$ initial states

$R(X, X')$ transition relation

$B(X)$ bad/target states

Satisfiability vs Verification

(or, combinational vs sequential)



- ◆ Given representation as SMT formulae $I(X)$, $R(X, X')$, $B(X)$
- ◆ Bounded model checking
 - State variables replicated K times
 - » $X_0, X_1, \dots, X_{k-1}, X_k$
 - Look for bugs of increasing length
 - » $I(X_0) \wedge R(X_0, X_1) \wedge \dots \wedge R(X_{k-1}, X_k) \wedge B(X_k)$
 - » bug if satisfiable
 - » increase k until ...
- ◆ Many other verification techniques
 - K -induction
 - Interpolation
 - Abstraction/refinement
 - IC3
- ◆ Several enhancements for hybrid systems
 - use local time for each automaton
 - guided search for scenario-based analysis

- ◆ The MathSAT SMT solver
 - <http://mathsat.fbk.eu>
- ◆ The NuSMV model checker
 - <http://nusmv.fbk.eu>
 - Forthcoming: a MathSAT-based extension of NuSMV
- ◆ Successfully applied in
 - OMC-ARE, COMPASS, AUTOGEF, FAME, FOREVER
 - » Support by the European Space Agency
 - Industrial technology transfer
 - » Avionics, railways, oil and gas

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Questions so far?